

Plane is nothing but a locus of a line with conditions.  
 of a line (in  $xy$  plane) sweeping along  $z$  axis  
 then the locus of the line makes a surface called plane.

Theorem: Prove that every linear equation in three variables  $x, y, z$  always represents a plane.

Proof: We assume a linear equation in three variables  $x, y$  and  $z$   
 i.e.  $ax + by + cz + d = 0$  ————— (1)  
 Here  $a, b, c$  &  $d$  are constants and one of the constants  $a, b$  and  $c$  is not zero.

Now: Let  $(x_1, y_1, z_1)$  and  $(x_2, y_2, z_2)$  be the co-ordinates of any two points lying on the locus of eqn (1)

then  $ax_1 + by_1 + cz_1 + d = 0$  ————— (2)

&  $ax_2 + by_2 + cz_2 + d = 0$  ————— (3)

We multiply eqn (2) by  $m_2$  and eqn (3) by  $m_1$  and adding we get  $(ax_1 + by_1 + cz_1 + d)m_2 + (ax_2 + by_2 + cz_2 + d)m_1 = 0$

$$\Rightarrow a(m_1x_1 + m_2x_2) + b(m_1y_1 + m_2y_2) + c(m_1z_1 + m_2z_2) + d(m_1 + m_2) = 0$$

$$\Rightarrow a \frac{(m_1x_1 + m_2x_2)}{m_1 + m_2} + b \frac{(m_1y_1 + m_2y_2)}{m_1 + m_2} + c \frac{(m_1z_1 + m_2z_2)}{m_1 + m_2} + d = 0$$

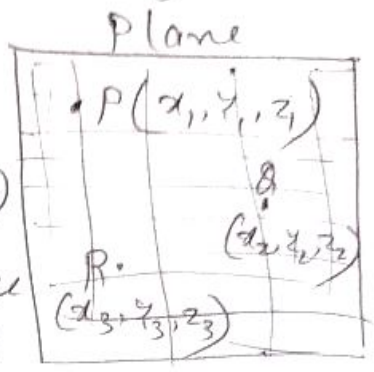
It means:- the points  $\left( \frac{m_1x_1 + m_2x_2}{m_1 + m_2}, \frac{m_1y_1 + m_2y_2}{m_1 + m_2}, \frac{m_1z_1 + m_2z_2}{m_1 + m_2} \right)$  satisfy the equation (1) means this point lies on the locus of eqn (1).  
 when  $m_1, m_2 \neq 0$

Hence the line joining  $(x_1, y_1, z_1)$  and  $(x_2, y_2, z_2)$  completely lies on the locus of (1) this points divides the line joining in the ratio  $m_1 : m_2$  also  
 Hence this locus is a plane.

B.Sc - I 26.4.21 B.Sc - Maths 11:30 AM to 12:15  
Topic: The plane in 3D.

Theorem: Find the equation of a plane passing through three given non-collinear points.

Assume - we assume three given non-collinear points are P, Q and R whose co-ordinates are  $(x_1, y_1, z_1)$ ,  $(x_2, y_2, z_2)$  and  $(x_3, y_3, z_3)$  respectively.



Let the equation of the plane through these points be  $ax + by + cz + d = 0$  — (1)

Now, since the points (assumed) lie in the plane eqn (1) the co-ordinates of the points P, Q & R must satisfy the eqn (1).

(1) i.e.,  $ax_1 + by_1 + cz_1 + d = 0$  — (2)

$ax_2 + by_2 + cz_2 + d = 0$  — (3)

$ax_3 + by_3 + cz_3 + d = 0$  — (4)

We have to eliminate constants, a, b, c & d, by which.

$$\begin{vmatrix} x & y & z & 1 \\ x_1 & y_1 & z_1 & 1 \\ x_2 & y_2 & z_2 & 1 \\ x_3 & y_3 & z_3 & 1 \end{vmatrix} = 0$$

Other method, eqn (2) - (3), (3) - (4), (4) - (2) which is very tedious.

————— (5)

Equation (5) is of the first degree in x, y, z and therefore represents a plane. Hence the result.

$R_1 \rightarrow R_1 - R_2, R_2 \rightarrow R_2 - R_3, R_3 \rightarrow R_3 - R_4$  method

$$\begin{vmatrix} x - x_1 & & & \\ & & & \\ & & & \\ & & & \end{vmatrix}$$